1.11.5

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## Unit 1

Chapter 1:	Spur and Helical Gears	1-1 to 1-90
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**Syllabus: Introduction to gears:** Material selection for gears, Modes of gear tooth failure, Gear Lubrication Methods.

**Spur Gears :** Number of teeth and face width, Force analysis, Beam strength (Lewis) equation, Velocity factor, Service factor, Load concentration factor, Effective load on gear, Wear strength (Buckingham's) equation, Estimation of module based on beam and wear strength, Estimation of dynamic tooth load by velocity factor and Buckingham's equation. AGMA (American Gear Manufacturing Association) approach of Gear design (Only mathematical relations, no numerical). Force analysis of Helical Gear, Beam Strength of Helical Gear, Wear strength and estimation of effective load based on Velocity factor (Barth factor) and Buckingham's equation. (No numerical on force analysis of helical)

1.1	Introduction1-2	
1.2	Classification of Gears1-2	
1.2.1	Comparison of Worm Gears and Crossed	
	Helical Gears1-4	
1.3	Selection of Type of Gears1-4	
1.4	Spur Gear Terminology1-5	
1.5	Minimum Number of Teeth to Avoid	
	Interference1-8	
1.5.1	Addendum Modification (Unequal Addenda) 1-9	
1.6	Standard Systems of Gear Tooth1-9	
1.7	Effects of Pressure Angle1-10	
1.8	Force Analysis of Spur Gears1-10	
1.9	Types (Modes) of Gear Tooth Failure1-11	
1.10	Gear Materials1-13	
1.10.1	Desirable Properties of Gear Material 1-13	
1.10.2	Gear Materials1-14	
1.11	Beam Strength of Spur Gear Tooth1-16	
1.11.1	Assumptions in Analysis of Beam Strength 1-16	
1.11.2	Lewis Equation for Beam Strength of Spur	
	Gear Tooth1-16	
1.11.3	Lewis Form Factor (Y)1-17	
1.11.4	Bending Endurance Strength ( $\sigma_b$ ) 1-18	

1.11.6	Weaker of Gear and Pinion1-19
1.12	Wear Strength of Spur Gear Tooth1-19
1.12.1	Load-Stress Factor (K)1-19
1.12.2	Ratio Factor (Q)1-20
1.13	Effective Load on Spur Gear Tooth1-20
1.13.1	Theoretical Tangential Force (F $_{t})$ 1-20
1.13.2	Maximum Tangential Force (F <sub>tmax</sub> )1-20
1.13.3	Dynamic Load on Gear Tooth and its Causes1-21
1.13.4	IS Gear Grades1-21
1.13.5	Methods of Estimation of Dynamic Load
	and Effective Load1-22
1.14	Safety of Gear Pair1-24
1.15	Design of Spur Gear Pair1-24
1.16	Power Transmitting Capacity of Spur
	Gear Pair1-40
1.17	Gear Lubrication1-53
1.17.1	Purpose of Gear Lubrication1-53
1.17.2	Lubricants Used in Gears1-53
1.17.3	Modes of Gear Lubrication1-54
1.17.4	Heat Dissipation1-54
1.18	Multi-Stage Gear Reducer1-54
1.19	AGMA (American Gear Manufacturers
	Association) Approach of Gear Design1-55
1.19.1	AGMA Stress Equations1-55
1.19.2	AGMA Strength Equations1-55
1.19.3	Safety of Gear Pair1-56
1.20	List of Formulae of Spur Gears1-56
1.21	Difference between Spur and Helical Gears1-58
1.22	Types of Helical Gears1-58
1.23	
	Advantages and Limitations
1.24	Advantages and Limitations of Helical Gears1-59 Helical Gear Terminology1-59

**Equivalent Spur Gear and Formative** 

**Minimum Number of Teeth on Helical** 

(Virtual) Number of Teeth .....1-62

Pinion.....1-64

Force Analysis of Helical Gears .....1-64

Beam Strength of Helical Gear Tooth.....1-66

Face Width (b) .....



2.8.1

1.28.1	Lewis Form Factor Based on Virtual
	Number of Teeth (Y')1-67
1.28.2	Bending Endurance Strength 1-67
1.28.3	Face Width1-67
1.28.4	Weaker of Gear and Pinion1-67
1.29	Wear Strength of Helical Gear Tooth1-68
1.30	Effective Load on Helical Gear Tooth1-69
1.30.1	Theoretical Tangential Force ( $F_t$ )1-69
1.30.2	Maximum Tangential Force ( $F_{tmax}$ ) 1-69
1.30.3	Methods of Estimation of Dynamic
	Load and Effective Load1-69
1.31	Safety of Helical Gear Pair1-71
1.32	List of Formulae of Helical Gears1-89

Unit 2

Chapter 2: Bevel and Worm Gears 2-1 to 2-62

Syllabus: Types of Bevel gears, Terminology, Virtual number of teeth, and force analysis of Straight Bevel Gear. Design of Straight Bevel Gear based on Beam Strength, Wear strength and estimation of effective load based on Velocity factor (Barth factor) and Buckingham's equation. (Simple numerical to be taken no design calculations) Worm and worm gear terminology and proportions of worm and worm gears, Force analysis of worm gear drives, Friction in Worm gears, efficiency of worm gears, Worm and worm gear material, Strength and wear ratings of worm gears (Bending stress factor, speed factor, surface stress factor, zone factor) IS 1443-1974, Thermal consideration in worm gear drive. (Simple numerical to be taken no design calculations)

2.1	Introduction to Bevel Gears2-2
2.2	Terminology of Bevel Gears2-2
2.3	Formative Number of Teeth
	(Tredgold's Proximation)2-5
2.4	$\label{lem:minimum Number of Teeth on Bevel Pinion2-5} \\$
2.5	Force Analysis of Straight Bevel Gears2-5
2.6	Types (Modes) of Bevel Gear Tooth Failure2-7
2.7	Materials for Bevel Gears2-7
2.8	Beam Strength of Straight Bevel Gear Tooth2-7

	Number of Teeth (Y')2-8
2.8.2	Permissible Bending Stress2-9
2.8.3	Face Width
2.8.4	Weaker of Gear and Pinion2-9
2.9	Wear Strength of Straight Bevel Gear Tooth 2-9
2.9.1	Load-Stress Factor (K)2-10
2.10	Effective Load on Straight Bevel Gear Tooth2-10
2.10.1	Theoretical Tangential Force (F <sub>t</sub> )2-10
2.10.2	Maximum Tangential Force (F <sub>tmax</sub> )2-10
2.10.3	Methods of Estimation of Dynamic Load and
	Effective Load on Straight Bevel Gear Tooth2-11
2.11	Safety of Bevel Gear Pair2-12
2.12	Types of Bevel Gears2-25
2.13	Mounting of Bevel Gears2-28
2.14	List of Formulae of Bevel Gears2-29
2.15	Introduction to Worm Gears2-31
2.16	Advantages and Limitations of
	Worm Gear Drives2-31
2.17	Terminology of Worm and Worm Gears2-32
2.17	Terminology of worm and worm dears2-32
2.17	Designation of Worm and Worm Gear Pair2-36
2.18	Designation of Worm and Worm Gear Pair2-36
2.18	Designation of Worm and Worm Gear Pair2-36 Force Analysis of Worm and Worm
2.18 2.19	Designation of Worm and Worm Gear Pair2-36 Force Analysis of Worm and Worm Gear Pair2-37
<ul><li>2.18</li><li>2.19</li><li>2.19.1</li></ul>	Designation of Worm and Worm Gear Pair2-36 Force Analysis of Worm and Worm Gear Pair2-37 Components of Force Acting on Worm2-37
2.18 2.19 2.19.1 2.19.2	Designation of Worm and Worm Gear Pair2-36 Force Analysis of Worm and Worm Gear Pair2-37 Components of Force Acting on Worm2-37 Components of Force Acting on Worm Gear2-38
2.18 2.19 2.19.1 2.19.2	Designation of Worm and Worm Gear Pair2-36 Force Analysis of Worm and Worm Gear Pair2-37 Components of Force Acting on Worm2-38 Direction of Components of Forces on
2.18 2.19 2.19.1 2.19.2 2.19.3	Designation of Worm and Worm Gear Pair2-36 Force Analysis of Worm and Worm Gear Pair
2.18 2.19 2.19.1 2.19.2 2.19.3	Designation of Worm and Worm Gear Pair2-36 Force Analysis of Worm and Worm Gear Pair
2.18 2.19 2.19.1 2.19.2 2.19.3 2.20	Designation of Worm and Worm Gear Pair2-36 Force Analysis of Worm and Worm Gear Pair
2.18 2.19 2.19.1 2.19.2 2.19.3 2.20	Designation of Worm and Worm Gear Pair2-36 Force Analysis of Worm and Worm Gear Pair
2.18 2.19 2.19.1 2.19.2 2.19.3 2.20 2.21	Designation of Worm and Worm Gear Pair2-36 Force Analysis of Worm and Worm Gear Pair
2.18 2.19 2.19.1 2.19.2 2.19.3 2.20 2.21 2.22	Designation of Worm and Worm Gear Pair2-36 Force Analysis of Worm and Worm Gear Pair
2.18 2.19 2.19.1 2.19.2 2.19.3 2.20 2.21 2.22 2.22.1	Designation of Worm and Worm Gear Pair2-36 Force Analysis of Worm and Worm Gear Pair
2.18 2.19 2.19.1 2.19.2 2.19.3 2.20 2.21 2.22 2.22.1 2.22.2	Designation of Worm and Worm Gear Pair2-36 Force Analysis of Worm and Worm Gear Pair
2.18 2.19 2.19.1 2.19.2 2.19.3 2.20 2.21 2.22 2.22.1 2.22.2	Designation of Worm and Worm Gear Pair2-36 Force Analysis of Worm and Worm Gear Pair
2.18 2.19 2.19.1 2.19.2 2.19.3 2.20 2.21 2.22 2.22.1 2.22.2 2.23	Designation of Worm and Worm Gear Pair2-36  Force Analysis of Worm and Worm  Gear Pair

Lewis Form Factor Based on Virtual



3.5.1

	Unit 3
2.30	List of Formulae of Worm Gears2-61
2.29.2	Lubricants Used in Worm Gears2-61
2.29.1	Purpose of Worm Gear Lubrication2-61
2.29	Lubrication of Worm Gears2-60
2.28	Types of Worm and Worm Gears2-60
2.27	Arrangements of Worm Gear Reducer2-59
	Gear Drive2-52
2.26	Thermal Considerations in Worm
2.25.2	Wear Strength Rating of Worm Gear - IS 7443 2-50
2.25.1	Beam Strength Rating of Worm Gear - IS 7443 2-49
	and Worm Gear Drive (IS 7443)2-49
2.25	Power (Load) Rating of Worm
2.24.4	Why Worm Gear Always Governs the Design? 2-49
	and Worm Wheel?2-48
2.24.3	Why Dissimilar Materials for Worm
2.24.2	Materials for Worm Gears2-48

## Chapter 3: Sliding Contact and Rolling Contact Bearings 3-1 to 3-83

**Syllabus :** Sliding contact bearing (Theoretical treatment only): Introduction to sliding contact bearing, classification, Reynolds's equation (2D), Petroff's equations, Sommerfeld number, Parameters of bearing design. Types of Rolling Contact Bearings and its selection, Static and Dynamic Load Carrying Capacities, Stribeck's Equation, Equivalent Bearing Load, Load - Life Relationship, Selection of Bearing Life, Selection of Rolling Contact Bearings from Manufacturer's Catalogue, Design for Cyclic Loads, Types of failure in rolling contact bearings - causes and remedies. (Simple Numerical treatment).

3.1	Lubrication and Lubricants3-2
3.1.1	Functions of Lubricants3-2
3.2	Physical and Chemical
	Properties of Lubricants3-2
3.3	Viscosity3-2
3.3.1	Measures of Viscosity3-3
3.4	Desirable Properties of Lubricant3-4
3.5	Classification of Lubricants3-5

3.5.2	Greases
3.5.3	Solid Lubricants3-6
3.6	Selection of Lubricants3-6
3.7	Basic Modes of Lubrication3-7
3.8	Types of Sliding Contact Bearings3-8
3.8.1	Classification of Sliding Contact Bearings
	Based on Mode of Lubrication3-8
3.8.2	Classification of Sliding Contact Bearings
	Based on Relative Motion between
	Contacting Surfaces3-10
3.9	Petroff's Equation for Hydrodynamic
	Journal Bearings3-11
3.10	Nomenclature (Terminology) of
	Hydrodynamic Journal Bearing3-12
3.11	Regimes (Theory) of
	Hydrodynamic Lubrication3-14
3.12	Reynold's Equation for Hydrodynamic
	Lubrication3-15
3.12.1	Assumptions in Reynold's Equation3-15
3.12.2	Reynold's Equation for Two-Dimensional Flow3-15
3.13	Types of Hydrodynamic Journal Bearings3-18
3.14	Design Considerations in Finite Length
	Hydrodynamic Journal Bearings3-18
3.15	Relations of Variables for Finite Length
	Hydrodynamic Journal Bearings
	(Raimondi and Boyd Method)3-19
3.15.1	Design and Performance Variables3-19
3.15.2	Dimensionless Parameters3-20
3.16	Temperature Rise in Finite Length
	Hydrodynamic Bearings with
	Feed Lubrication3-21
3.16.1	Total flow of Lubricating oil (Q)3-22
3.16.2	Rate of Heat Generation ( $H_g$ )3-22
3.16.3	Rate of Heat Dissipation ( $H_d$ )3-22
3.16.4	Temperature Rise (ΔT)3-23

Lubricating Oils (Liquid Lubricants) .....



3.16.5	Viscosity of Lubricating Oil ( $\mu$ )	
3.16.6	Average Temperature of Lubricating Oil (Tav) 3-23	
3.17	Temperature Rise in Finite Length	
	Hydrodynamic Self-Contained or Self-Cooled	
	Bearings3-23	
3.18	Selection of Bearing Design Variables for	
	Finite Length Hydrodynamic Journal	
	Bearings3-25	
3.19	List of Formulae of Sliding Contact	
	Bearings3-33	
3.20	Introduction to Bearings3-34	
3.20.1	Types of Bearings3-34	
3.21	Nomenclature of Rolling Contact Bearing $3-34$	
3.22	Types of Loads on Rolling Contact	
	Bearings3-35	
3.23	Types of Rolling Contact Bearings3-35	
3.23.1	Ball Bearings	
3.23.2	Roller Bearings	
3.23.3	Comparison between Ball and Roller Bearings $\dots 338$	
3.23.4	Applications of Rolling Contact Bearings3-39	
3.24	$Designation\ of\ Rolling\ Contact\ Bearings\3-40$	
3.25	Factors Affecting Selection of	
	Bearing Type 3-40	
3.26	Basic Static Capacity (Basic Static Load	
	Rating) of Bearings (Co) 3-41	
3.27	Stribeck's Equation for Basic Static	
	Capacity of Bearings 3-42	
3.28	Equivalent Static Load3-43	
3.29	Bearing Life	
3.30	Basic Dynamic Capacity (Basic Dynamic Load	
	Rating) Of Bearings (C)3-45	
3.31	Equivalent Dynamic Load (P <sub>e</sub> )3-45	
3.32	Load-Life Relationship3-46	
3.33	Selection of Bearing Life3-46	
3.34	Selection of Bearing from	
	Manufacturer 'S Catalogue 3-47	

3.35	Bearings with Probability of Survival	
	Higher than 90 Percent3-	56
3.35.1	Adjusted Life of Bearing3-	56
3.35.2	Reliability of Bearing System3-	56
3.36	<b>Equivalent Dynamic Load for Bearing</b>	
	Under Cyclic Loads3-	65
3.37	<b>Equivalent Dynamic Load for Continuously</b>	
	Variable Cyclic Loads3-	75
3.38	Mounting of Bearings3-	76
3.39	Taper Roller Bearing3-	77
3.39.1	Nomenclature of Taper Roller Bearing3-	77
3.39.2	Mounting of Taper Roller Bearings3-	78
3.40	Preloading of Bearings3-	78
3.40.1	Objectives (Purpose) of Preloading3-	78
3.40.2	Methods of Preloading3-	78
3.41	Failure of Rolling Contact Bearings3-	79
3.41.1	Types (Modes) of Failures of Rolling	
	Contact Bearings3-	79
3.42	Comparison of Sliding and Rolling	
	Contact Bearing3-	80
3.43	List of Formulae of Rolling	
	Contact Bearings3-	83
	Unit 4	
	Offic 4	

Chapter 4: Design of Clutches and Brakes 4-1 to 4-66

Syllabus: Clutches: Introduction, Types of clutches, Material, Positive clutches, friction clutches, single plate, multiple plate, Cone clutch, and centrifugal clutches, Application of friction clutches automotive and industrial machinery sector. (Only Theoretical Treatment)

Brakes: Introduction, Types of brakes, Material, Design of band brake, external and internal shoe breaks, internal expanding shoe brakes, design of disc brakes. Application of brakes in automotive and industrial machinery sector. (Only Theoretical Treatment)

4.1	Introduction to Clutch	4-2
4.2	Classification of Clutches	4-2
4.2.1	Positive Clutches	4-2

4.2.2	Friction Clutches4-2
4.3	Requirements of Good Friction Clutch4-3
4.4	Classification of Friction Clutches4-3
4.5	Plate (Disk) Clutches4-4
4.5.1	Torque Transmitting Capacity of Plate Clutch 4-4
4.5.2	Pairs of Contacting Surfaces in Plate Clutch4-5
4.6	Types of Plate (Disk) Clutches4-5
4.6.1	Single Plate (Disk) Clutches4-5
4.6.2	Multi-Plate (Disk) Clutches4-7
4.7	Cone Clutches4-13
4.7.1	Construction of Cone Clutch 4-13
4.7.2	Torque Transmitting Capacity of Cone Clutch 4-14
4.7.3	Disengagement Force for Cone Clutch 4-15
4.7.4	Semi-Cone Angle 4-15
4.7.5	Advantages and Limitations of Cone Clutches 4-15
4.8	Centrifugal Clutches4-19
4.8.1	Design of Centrifugal Clutch4-20
4.9	Friction Materials4-22
4.9.1	Characteristics of Good Friction Material 4-22
4.9.2	Types of Friction Materials 4-22
4.10	Temperature Rise in Clutch Operation 4-24
4.11	Applications of Friction Clutches4-25
4.12	List of Formulae of Clutches4-25
4.13	Introduction to Brake4-26
4.14	Braking Torque4-26
4.14.1	Energy Absorbed by Brake4-27
4.14.2	Required Braking Torque Capacity4-28
4.15	<b>Heat Dissipation and Temperature</b>
	Rise in Brake Operation4-28
4.16	Classification of Brakes4-31
4.17	Block Brakes (External Brakes)4-31
4.17.1	Block or Shoe Brake with Short Shoe4-32
4.17.2	Double Block or Shoe Brake4-35
4.17.3	Pivoted Block or Shoe Brake with Long Shoe 4-40 $$
4.17.4	Pivoted Double Block or Shoe Brake 4-43
4.18	Internal Expanding Shoe Brakes4-44
4.18.1	Construction of Internal Expanding
	Shoe Brake 4-45

4.18.2	Analysis of Internal Expanding Shoe Brake4-4
4.19	Disk Brakes4-53
4.19.1	Advantage of Disk-Brakes4-53
4.19.2	Caliper Disk Brakes4-54
4.19.3	Design of Caliper Disk Brake4-54
4.20	Band Brakes4-58
4.20.1	Simple Band Brake4-58
4.20.2	Differential Band Brake4-60
4.20.3	Back-Stop Brake4-60
4.20.4	Standard Dimensions of Brake Drum4-6
4.21	Applications of Brakes4-65
4.22	List of Formulae of Brakes4-65

## Chapter 5 : Design of Machine Tool Gear Boxes 5-1 to 5-51

Unit 5

**Syllabus**: Introduction to Machine Tool Gearboxes, classification, basic considerations in design of drives and its Applications, Determination of variable speed range, Graphical representation of speed and structure diagram, Ray diagram, selection of optimum ray diagram, Kinematic /Gearing Diagram, Deviation diagram, Difference between numbers of teeth of successive gears in a change gear box. (Note: Full design problem to be restricted up to 2 Stages only & amp: No design problem on deviation diagram)

only & amp, to design problem on deviation diagram,		
Introduction to Gear Boxes5-2		
Purpose of Using Gear Box5-2		
Types of Gear Boxes5-2		
Need of Multi-Speed Gear		
Box in Machine Tools5-3		
Basic Considerations in Design of		
Multi-Speed Gear Box5-4		
Laws of Stepped Regulation of Speeds in		
Multi-Speed Gear Box5-4		
Comparison of Laws of Stepped Regulation of		
Speeds in Multi-Speed Gear Box5-7		
Advantages (Significance) of Geometric		
Progression5-7		
Parameters Required (Used) in Kinematic		
Design of Multi-Speed Gear Box5-9		

5.6	Kinematic Diagram (Gearing Diagram) of
	Gear Box 5-12
5.7	Structural Formulae 5-12
5.8	Structure Diagrams5-14
5.8.1	Procedure for Constructing Structure Diagram 5-14
5.8.2	Examples of Structure Diagram5-14
5.8.3	Salient Features and Limitations of
	Structure Diagrams 5-15
5.8.4	Types of Structure Diagrams 5-15
5.8.5	Selection of Optimum Structure Diagram5-15
5.9	Speed Diagrams and Ray Diagrams 5-17
5.9.1	Procedure for Constructing Speed Diagrams 5-17
5.9.2	Salient Features of Speed Diagrams 5-17
5.9.3	Selection of Optimum Speed Diagram 5-17
5.9.4	Comparison between Structure
	Diagram and Speed Diagrams 5-18
5.10	General Guidelines in Developing
	Kinematic Diagram (Gearing Diagram) for
	Multi-Speed Gear Box5-19
5.11	<b>Procedure for Kinematic Design of</b>
	Multi-Speed Gear Box For Machine Tools 5-20
5.12	Deviation Diagram for Multi-Speed
	Gear Box 5-22
5.13	List of Formulae5-51

Unit 6

## Chapter 6: Transmission system in Hybrid **Electric Vehicle** 6-1 to 6-14

**Syllabus :** Introduction, Types of Hybrid Electric Vehicles: Basic Classification, Basic Modes of Operation, Other Derivatives, Degree of Hybridization. Power Split Devices (PSD): Simple and EM compound PSD, HEV Component Characteristics: The IC Engine, Electric Machines, Battery, HEV Performance Analysis: Series HEV, Parallel HEV, HEV Component Sizing: General Considerations, Sizing for Performance, Optimum Sizing, Power Management: Control Potential, Control.

6.1	Electric Vehicles6-2
6.2	Battery Electric Vehicles (BEV)6-2
6.3	Hybrid Electric Vehicles (HEV)6-4
6.4	Classification of Hybrid Electric
	Vehicles (HEVs) 6-4
6.4.1	Classification Based on Architecture 6-4
6.4.2	Classification. Based on Degree of
	Hybridization6-6
6.4.3	Classification Based on Nature of Power
	Source 6-6
6.5	Advantages and Limitations of Hybrid
	Electric Vehicles6-7
6.6	Power Split Device (PSD)6-7
6.6.1	Layout of Power Slit Device6-7
6.6.2	Functions of Power Split Device6-8
6.7	Types of Power Split Devices6-8
6.7.1	Simple Power Split Device6-8
6.7.2	Compound Power Split Device6-8
6.8	Components of Series Hybrid
	Electric Vehicles6-9
6.8.1	Components of Series Hybrid Electric Vehicles 6-9
6.8.2	Operations of Series Hybrid Electric Vehicles6-10
6.9	Components of Parallel Hybrid
	Electric Vehicles6-11
6.10	Component Sizing of Hybrid
	Electric Vehicles6-12
6.10.1	Sizing of Electronic Motor6-12
6.10.2	Sizing of Battery Pack6-13
6.11	Modes of Operation of Hybrid
	Electric Vehicles6-13
6.12	Power Management6-14